Simulation-based procedure for predictor's selection - integrating machine-learning and model-based approach in survey sampling

Alicja Wolny-Dominiak, Tomasz Żądło

Department of Statistical and Mathematical Methods in Economics Department of Statistics, Econometrics and Mathematics University of Economics in Katowice

The work has been co-financed by the Minister of Science under the "Regional Initiative of Excellence" programme.



Minister of Science Republic of Poland



Tzavidis et al. (2018) propose a three-stage framework for the production of small area official statistics:

- STAGE 1: specification
 - specify user needs
 - data availability and geographical coverage
- STAGE 2: analysis & adaptation
 - initial triplet of estimates
 - use of models for small area estimation
 - model building
- STAGE 3: evaluation
 - uncertainty assessment
 - method evaluation design-based (or model-based) simulation study

- Introduction
- Predicting a function of the response variable the ex-ante approach
- The proposed WASP method
- Real-data application

Table: Terms in survey sampling vs machine learning

survey sampling	machine learning
auxiliary variable	predictor
class of predictors	predictive algorithm / prediction method
predictor	prediction strategy
multivariate predictor	joint prediction strategy

Models:

- parametric,
- nonparametric.

Various predictive algorithms (predictors), e.g.:

- BLUPs and EBLUPs,
- BPs and EBPs,
- PLUG-IN.

Ex-ante approach:

- usage of various accuracy measures, e.g. prediction RMSE, QAPE,
- selection based on voting.

WASP:

Voting-based ex-Ante method for Selecting joint Prediction strategy

Example of a voting matrix for S voters choosing one of P candidates

	candidate 1	candidate 2	 candidate P
voter 1	<i>v</i> ₁₁	<i>v</i> ₁₂	 V _{1P}
voter 2	<i>v</i> ₂₁	V ₂₂	 V _{2P}
voter S	v _{S1}	V _{S2}	 VSP

Example of a matrix of values of accuracy measures for P prediction strategies under S simulation scenarios

	strategy 1	strategy 2	 strategy P
simulation scenario 1	<i>r</i> ₁₁	<i>r</i> ₁₂	 r _{1P}
simulation scenario 2	<i>r</i> ₂₁	<i>r</i> ₂₂	 r _{2P}
simulation scenario S	<i>r</i> _{S1}	<i>r</i> ₅₂	 r _{SP}

A method with the following features:

- joint prediction of any vector of characteristics,
- using a set of any ex-ante prediction accuracy measures,
- utilizing any type of data (cross-sectional, longitudinal, time-series),
- considering various scenarios for out-of-sample data (also not observed in the sample) defined by any class of models (both parametric and nonparametric models can be used simultaneously).
- different proposals of selection criteria.

 \ldots to be used in any prediction problem (not only in survey sampling).

Two sets:

• *S* of *n* sample observations

•
$$\mathbf{X}_{S} = [x_{ij}]_{n \times q}$$
 - known, fixed
• $\mathbf{y}_{S} = [y_{1} \ y_{1} \ \dots \ y_{n}]^{T}$ - a realization of
 $\mathbf{Y}_{S} = [Y_{1} \ Y_{1} \ \dots \ Y_{n}]^{T}$

• R of k out-of-sample observations

• $\mathbf{X}_R = [x_{ij}]_{k \times q}$ - known or assumed, fixed • $\mathbf{Y}_R = [Y_1 \ Y_1 \ \dots \ Y_k]^T$ - random with unknown realizations

Let
$$\mathbf{Y} = [\mathbf{Y}_S^T \ \mathbf{Y}_R^T]^T$$
 and $\mathbf{X} = [\mathbf{X}_S^T \ \mathbf{X}_R^T]^T$.

The aim: prediction of a vector of characteristics:

$$\boldsymbol{\theta} = \begin{bmatrix} \theta^{(1)}(\mathbf{Y}) & \theta^{(2)}(\mathbf{Y}) & \dots & \theta^{(C)}(\mathbf{Y}) \end{bmatrix}^T, \quad (1)$$

where c = 1, ..., C.

An example of a regression model:

$$\begin{cases} \mathbf{Y} = \mathbf{h}(\mathbf{X}) + \boldsymbol{\xi} \\ E(\boldsymbol{\xi}) = \mathbf{0} \\ Var(\boldsymbol{\xi}) = \mathbf{V} \end{cases}$$
(2)

where h(.) is a fixed but unknown function of independent variables, $\boldsymbol{\xi}$ is a random term with **0** mean and unknown variance-covariance matrix **V**.

Special cases of (2) include e.g.:

- the multiple regression model (Baltagi, 2021),
- the linear mixed model (Jiang, 2007),
- machine learning models (Hastie et al., 2009).

 $\hat{H}^{(g)}(.)$ - an estimator of h(.) based on gth model $M^{(g)}(\mathbf{Y}, \mathbf{X})$. $\hat{h}^{(g)}(.)$ - an estimate i.e. the realization of $\hat{H}^{(g)}(.)$.

If the *g*th model is either parametric or nonparametric, the estimates of h(.) will be denoted by $\hat{h}_{PAR}^{(g)}(.)$ or $\hat{h}_{NPAR}^{(g)}(.)$, respectively.

The PLUG-IN of C characteristics (1) under the gth model:

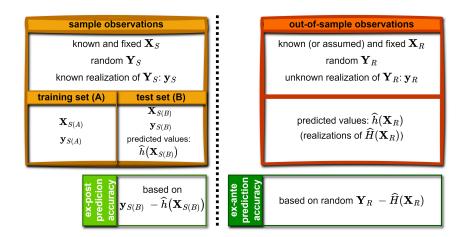
$$\hat{\boldsymbol{\theta}}_{PLUG-IN}^{(g)} = \begin{bmatrix} \hat{\boldsymbol{\theta}}_{PLUG-IN}^{(g,1)}(\mathbf{Y}_{S}) & \hat{\boldsymbol{\theta}}_{PLUG-IN}^{(g,2)}(\mathbf{Y}_{S}) & \dots & \hat{\boldsymbol{\theta}}_{PLUG-IN}^{(g,C)}(\mathbf{Y}_{S}) \end{bmatrix}^{T}, \quad (3)$$

where

$$\hat{\theta}_{PLUG-IN}^{(g,c)} = \hat{\theta}_{PLUG-IN}^{(g,c)}(\mathbf{Y}_{S}) = \theta^{(c)} \left(\begin{bmatrix} \mathbf{Y}_{S} \\ \hat{H}^{(g)}(\mathbf{X}_{R}) \end{bmatrix} \right), \quad (4)$$

 $\hat{H}(.)$ is an estimator of h(.) (see (2)).

Predicting a function of the response variable: two approaches to prediction accuracy



Predicting a function of the response variable: ex-ante prediction accuracy measures

The prediction error:

$$U = \hat{\theta}(\mathbf{Y}_{S}) - \theta(\mathbf{Y}) = \hat{\theta} - \theta$$

The prediction RMSE:

$$RMSE(\hat{\theta}) = \sqrt{E(\hat{\theta} - \theta)^2} = \sqrt{E(U^2)}$$
(5)

The *p*th **Q**uantile of **A**bsolute **P**rediction **E**rror (Żądło, 2013; Wolny-Dominiak i Żądło, 2022):

$$QAPE_{p}(\hat{\theta}) = \inf \left\{ x : P\left(\left| \hat{\theta} - \theta \right| \le x \right) \ge p \right\}$$
 (6)

This measure informs that at least p100% of observed absolute prediction errors are smaller than or equal to $QAPE_p(\hat{\theta})$, while at least (1-p)100% of them are higher than or equal to $QAPE_p(\hat{\theta})$.

qape R package on CRAN: 13 000 downloads

Predicting a function of the response variable: Bootstrap under parametric and nonparametric models

Generated bootstrap realizations of prediction errors:

$$U_{gen} = \hat{\theta}(\mathbf{y}_{s \, gen}) - \theta(\mathbf{y}_{gen}), \tag{7}$$

where \mathbf{y}_{sgen} and \mathbf{y}_{gen} , are generated sample and population vectors of the dependent variable, respectively.

Bootstrap under parametric model - the parametric bootstrap:

$$\mathbf{y}_{gen}^{(g,b)} = \hat{h}_{PAR}^{(g)}(\mathbf{X}) + \boldsymbol{\xi}_{gen}^{(g,b)}, \tag{8}$$

where g = 1, ..., G; b = 1, ..., B; $\hat{h}_{PAR}^{(g)}(.)$ is a parametric estimate of h(.) obtained based on the original sample under the assumption of the *g*th (here: parametric) model, $\xi_{gen}^{(g,b)}$ is a generated *b*th realisation of an error term from the estimated parametric distribution assumed for ξ under the *g*th model.

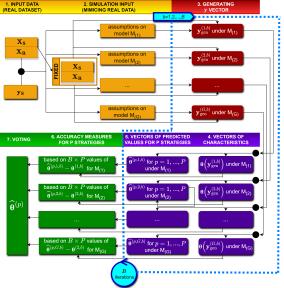
Predicting a function of the response variable: Bootstrap under parametric and nonparametric models

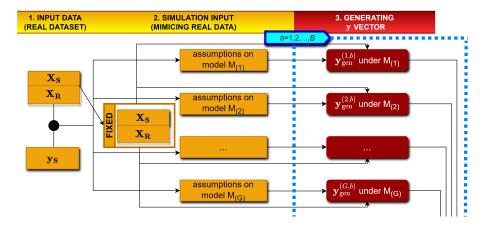
Bootstrap under nonparametric model (our proposal):

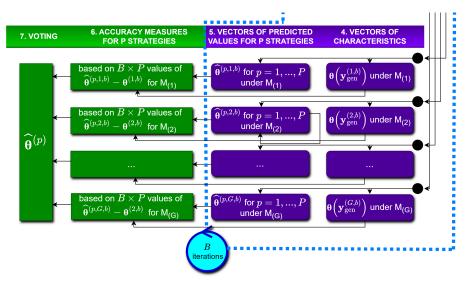
$$\mathbf{y}_{gen}^{(g,b)} = \hat{h}_{NPAR}^{(g)}(\mathbf{X}) + g\bar{\mathbf{e}}n^{(b)}(\hat{f}(\mathbf{r}_{S}^{(g)}), (n+k)), \tag{9}$$

where g = 1, ..., G; b = 1, ..., B; $\hat{h}_{NPAR}^{(g)}(.)$ is a nonparametric estimate of h(.) obtained based on the original sample under the assumption of the *g*th (here: nonparametric) model, $\hat{f}(\mathbf{r}_{S}^{(g)})$ is a kernel density estimate of the distribution of residuals $\mathbf{r}_{S}^{(g)}$ computed under the *g*th model, and $g\bar{e}n^{(b)}(\hat{f}(\mathbf{r}_{S}^{(g)}), (n+k))$ is a $(n+k) \times 1$ zero centred vector of values generated based on kernel estimate $\hat{f}(\mathbf{r}_{S}^{(g)})$ in the *b*th iteration.

The proposed WASP method







Values of accuracy measures obtained in the simulation form a matrix of size $S \times P$, where:

- S = G × C × M rows where G is the number of models used to generate data, C is the number of predicted characteristics, M is the number of considered accuracy measures ("voters"),
- *P* is the number of considered prediction strategies ("canditates").

It will be called the **accuracy measures matrix**, and it will be denoted by **A**

The first proposal: to mimic the first-past-the-post voting system (Felsenthal, 2012), where voters choose a single candidate, and the candidate with the highest number of votes wins the election.

 $\ensuremath{\textbf{Algorithm}}\xspace1$ The proposed first-past-the-post voting algorithm of the prediction strategy selection

The input is an accuracy measure matrix A.

- 1: for s in 1:S do
- 2: In the sth row of **A**, assign rank 1 for the prediction strategy with the minimum value of *m*th accuracy measure and rank 0 for the rest of the strategies.
- 3: end for
- 4: Write the resulting ranks as a voting matrix **W**₁ with *S* rows and *P* columns.
- 5: Compute column sums of the ranks for each out of *P* potential prediction strategies.
- 6: The prediction strategy with the highest sum is chosen.

The proposed WASP method: Algorithm 1

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	30,409.52	92,010.24	30,525.97	67,948.94	75,471.81	91,967.10
$M_6, \theta_1, RMSE$	33,892.15	82,222.11	33,973.64	79,599.19	78,954.10	82,234.57
$M_1, \theta_2, RMSE$	916.26	548.11	916.13	413.71	613.53	508.82

Table: Accuracy measures matrix A - the short form

Table: First-past-the-post voting matrix \mathbf{W}_1 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	1	0	0	0	0	0
$M_6, \theta_1, RMSE$	1	0	0	0	0	0
$M_1, \theta_2, RMSE$	0	0	0	1	0	0
sum	14	5	7	3	1	6

The second proposal: to mimic the Borda count system, which belongs to positional voting procedures (Felsenthal and Machover, 2012), where voters **order** candidates from the worst to the best, and in the original Borda count algorithm, the candidate with the highest sum/mean of points is elected.

In our proposal we choose candidate with the highest median because ranks are measured on the ordinal scale.

The usage of positional voting system (Felsenthal and Machover, 2012):

- in elections of the president of the Republic of Ireland,
- elections to the Australian House of Representatives,
- and some municipal elections in the United States.

 $\label{eq:algorithm 2} Algorithm \ 2 \ {\mbox{The proposed positional voting algorithm of the prediction strategy selection} \\$

The input is an accuracy measure matrix A.

- 1: for s in 1:S do
- 2: In the sth row of **A**, rank prediction strategies according to the values of the *m*th accuracy measure from 1 (the maximum value in this row) to *P* (the minimum value in this row).
- 3: end for
- 4: Write resulting ranks as a voting matrix **W**₁ with *S* rows and *P* columns.
- 5: Compute the median of ranks for each out of *P* prediction strategies.
- 6: The prediction strategy with the highest median rank is chosen.

The proposed WASP method - Algorithm 2

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	30,409.52	92,010.24	30,525.97	67,948.94	75,471.81	91,967.10
$M_6, \theta_1, RMSE$	33,892.15	82,222.11	33,973.64	79,599.19	78,954.10	82,234.57
$M_1, \theta_2, RMSE$	916.26	548.11	916.13	413.71	613.53	508.82

Table: Accuracy measures matrix A - the short form

Table: Positional voting matrix W_2 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	6	1	5	4	3	2
$M_6, \theta_1, RMSE$	6	2	5	3	4	1
$M_1, \theta_2, RMSE$	1	4	2	6	3	5
median	5	4	4	3	3	3

The third proposal: inspired by

- evaluative voting, also called **utilitarian voting** (Baujard et al. (2014)
- and Majority Judgement (Balinski and Laraki, 2007).

In evaluative voting, each voter evaluates all candidates by assigning an **ordinal grade** that reflects their suitability (the better the candidate the higher the grade). Hence, the same grade can be given to several candidates. The candidate with the highest total/mean grade is the winner.

The procedure of the Majority Judgement is similar but the highest median grade is the rule to choose the candidate.

In our approach the assessment is based on scaled accuracy measures (on a ratio scale) ...

 \ldots not based on the ranks (on the ordinal scale) as in the evaluating/utilitarian voting.

Scaled values of accuracy measures:

$$a'=1-a, \tag{10}$$

where a is a rescaled value (min-max normalization) of the considered accuracy measure.

Hence, $a' \in [0,1]$ and the higher the value of (10), the better is accuracy.

Algorithm 3 The proposed evaluative voting algorithm of the prediction strategy selection

The input is an accuracy measure matrix A.

- 1: for s in 1:S do
- 2: In the *s*th row of **A**, scale the values of the *m*th accuracy measure applying formula (10) to obtain *P*-values from interval [0, 1].
- 3: end for
- 4: Write resulting values as a matrix W_3 with S rows and P columns (called the voting matrix).
- 5: Compute the median of scaled values for each out of *P* prediction strategies.
- 6: the prediction strategy with the highest median value is chosen.

The proposed WASP method: Algorithm 3

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	30,409.52	92,010.24	30,525.97	67,948.94	75,471.81	91,967.10
$M_6, \theta_1, RMSE$	33,892.15	82,222.11	33,973.64	79,599.19	78,954.10	82,234.57
$M_1, \theta_2, RMSE$	916.26	548.11	916.13	413.71	613.53	508.82
		•••			•••	• • •

Table: Accuracy measures matrix **A** - the short form

Table: Scaled voting matrix W_3 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	1.000	0.000	0.998	0.391	0.268	0.001
$M_6, \theta_1, RMSE$	1.000	0.000	0.998	0.055	0.068	0.000
$M_1, \theta_2, RMSE$	0.000	0.733	0.000	1.000	0.602	0.811
median	0.999	0.454	0.997	0.650	0.318	0.401

 W_3 will be used in the Algorithm 4 too ...

The drawback of Algorithm 3 - it only considers the median of the results in the selection process, not the whole distribution.

Hence, our fourth proposal ...

The proposed WASP method: Algorithm 4

Algorithm 4 The proposed ECDF AUC-based voting algorithm of the prediction strategy selection

The input is an accuracy measure matrix **A**.

- 1: for s in 1:S do
- 2: In the *s*th row of **A**, scale the values of the *m*th accuracy measure applying formula (10) to obtain *P*-values from interval [0, 1].
- 3: end for
- 4: Write resulting values as a matrix W_3 with S rows and P columns (called the voting matrix).
- 5: Based on the values in the *p*th column, compute the ECDF for the scaled voting results obtained for the *p*th prediction strategy (where p = 1, 1, ..., P).
- 6: The prediction strategy with the smallest value of the area under the ECDF in interval [0, 1] is chosen.

Table: Scaled voting matrix W_3 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	1.000	0.000	0.998	0.391	0.268	0.001
$M_6, \theta_1, RMSE$	1.000		0.998	0.055	0.068	0.000
$M_1, \theta_2, RMSE$	0.000	0.733	0.000	1.000	0.602	0.811
ECDF	ECDF 1	ECDF 2	ECDF 3	ECDF 4	ECDF 5	ECDF 6
AUC in [0,1]	0.338	0.506	0.346	0.439	0.655	0.550

Input data - the portfolio from Polish insurance company for full 2007-2010 years (exposure = 1).

The longitudinal structure of data - each *i*th policy corresponds to the aggregate value of claims for single policy *Claim_Amount* and risk factors:

- Gender category: 1 (Female), 0 (Male)
- Kind_of_distr kind of district: urban, country, suburban
- Kind_of_payment category: cash, transfer
- Engine category: BEN, DIS
- Age_group category: 1, 2, 3.

Two key characteristics describing the portfolio of policies: total value of claims $\theta_{(1)}$, the median of claims $\theta_{(2)}$.

Automobile portfolio example

The joint prediction of characteristics $\theta_{(1)}$ and $\theta_{(2)}$ with WASP - assumptions:

- 1. First assumption how to obtain 'true' claims values
 - parametric *M_{PAR}*: GLM Gamma (GG), log-normal regression (LogN), GAM
 - non-parametric *M_{NPAR}*: decision tree (DT), SVM with linear kernel (SVML), SVM with polynomial kernel (SVMP)
- 2. Second assumption which predictive models
- 3. Third assumption which prediction algorithm for every predictive model

Strategy	Predictive model	Prediction algorithm
strategy 1	GG	PLUG-IN
strategy 2	LogN	PLUG-IN
strategy 3	GAM	PLUG-IN
strategy 4	DT	PLUG-IN
strategy 5	SVML	PLUG-IN
strategy 6	SVMP	PLUG-IN

Table: Description of candidate prediction strategies

4. Fourth assumption - the criteria for selecting a prediction strategy: RMSE, $QAPE_{0.5}$ and $QAPE_{0.95}$

Monte Carlo simulation to estimate ex-ante accuracy measures (5000 iterations) - single *b*th iteration stages:

- generating real values of the variable of *Claim_Amount* under 6 assumed 'true' models M₍₁₎, ..., M₍₆₎,
- calculating characteristics $\theta_{(1)}$ and $\theta_{(2)}$ for every generated "true" Claim_Amount,
- predicting characteristics $\theta_{(1)}$ and $\theta_{(2)}$ under 6 assumed models $M_{(1)}, ..., M_{(6)}$,
- calculating measures of ex ante prediction accuracy: *RMSE*, *QAPE*_{0.5}, *QAPE*_{0.95}.

In result, we obtain accuracy measures matrix A with 36 rows, as we involve 2 characteristics, 6 models and 3 accuracy measures.

Automobile portfolio example

VOTING results

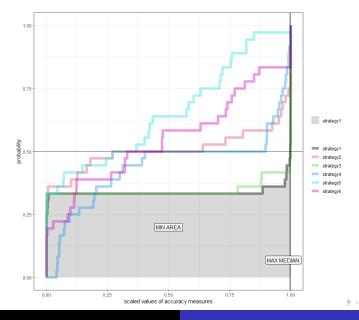
Four voting systems - the initiating step is to perform some transformation of the matrix \bf{A} to the voting matrix \bf{W} and then pointing the winner according to presented algorithms.

Prediction strategy	FPTP	Positional	Evaluative	ECDF AUC
strategy 1	14	5	0.999	0.338
strategy 2	5	4	0.454	0.506
strategy 3	7	4	0.997	0.346
strategy 4	3	3	0.650	0.439
strategy 5	1	3	0.318	0.655
strategy 6	6	3	0.401	0.550

Values of selection criteria for four voting systems

(a) sum of votes (the higher the better), (b) median of ranks (the higher the better), (c) median of scaled accuracy measures (the higher the better), (d) ECDF AUC (the smaller the better)

Automobile portfolio example: VOTING with ECDF AUC



E 990

Summing up, **strategy 1** is the winner in all voting systems. This means that the joint prediction of $\theta_{(1)}$ and $\theta_{(2)}$ should be performed using the **GLM-Gamma model**.

The prediction for 2011 amounts to $\hat{\theta}_{(1)} = 231,583.16$ and $\hat{\theta}_{(2)} = 3,141.69$.

Obtained assessments for the 'true' model GG

Accuracy Measure	$\theta_{(1)}$	$\theta_{(2)}$
RMSE	30,409.52	916.26
$QAPE_{0.5}$	20,337.75	829.49
$QAPE_{0.95}$	60,198.47	1,481.50

WASP METHOD



THANK YOU

References I

- Balinski, M. and Laraki, R. (2007). A theory of measuring, electing, and ranking. Proceedings of the National Academy of Sciences, 104(21):8720–8725. Publisher: Proceedings of the National Academy of Sciences.
- Baltagi, B. H. (2021). Econometrics. Classroom Companion: Economics. Springer International Publishing, Cham.
- Bauer, E. and Kohavi, R. (1999). An Empirical Comparison of Voting Classification Algorithms: Bagging, Boosting, and Variants. Machine Learning, 36(1):105–139.
- Baujard, A., Igersheim, H., Lebon, I., Gavrel, F., and Laslier, J.-F. (2014). Who's favored by evaluative voting? An experiment conducted during the 2012 French presidential election. Electoral Studies, 34:131–145.

References II

- Boubeta, M., Lombardía, M. J., and Morales, D. (2016). Empirical best prediction under area-level poisson mixed models. Test, 25(3):548–569.
- Brandt, F., Conitzer, V., Endriss, U., Lang, J., and Procaccia, A. D., editors (2016). Handbook of computational social choice. Cambridge University Press, New York, NY, USA.
- Burka, D., Puppe, C., Szepesváry, L., and Tasnádi, A. (2022). Voting: A machine learning approach. European Journal of Operational Research, 299(3):1003–1017.
- Butar, F. B. and Lahiri, P. (2003). On measures of uncertainty of empirical Bayes small-area estimators. Journal of Statistical Planning and Inference, 112(1-2):63–76.

References III

- Carpenter, J. R., Goldstein, H., and Rasbash, J. (2003). A novel bootstrap procedure for assessing the relationship between class size and achievement. Journal of the Royal Statistical Society: Series C (Applied Statistics), 52(4):431–443.
- Cassel, C.-M., Särndal, C.-E., and Wretman, J. H. (1977).
 Foundations of Inference in Survey Sampling.
 Wiley-Interscience, New York, 1st edition edition.
- Chambers, R. and Chandra, H. (2013). A Random Effect Block Bootstrap for Clustered Data. Journal of Computational and Graphical Statistics, 22(2):452–470.
- Chernick, M. R. and LaBudde, R. A. (2014). An Introduction to Bootstrap Methods with Applications to R. Wiley, 1st edition edition.

References IV

- Chwila, A. and Żądło, T. (2022). On properties of empirical best predictors. Communications in Statistics - Simulation and Computation, 51(1):220–253.
- Daneshvar, N. H.-N., Masoudi-Sobhanzadeh, Y., and Omidi, Y. (2023). A voting-based machine learning approach for classifying biological and clinical datasets. BMC Bioinformatics, 24(1):140.
- Dang, Q. and Yuan, J. (2023). A Kalman filter-based prediction strategy for multiobjective multitasking optimization. Expert Systems with Applications, 213:119025.
- De Jong, P. and Heller, G. Z. (2008). Generalized linear models for insurance data. Cambridge University Press.
- Denuit, M. and Lang, S. (2004). Non-life rate-making with bayesian gams. Insurance: Mathematics and Economics, 35(3):627–647.

References V

- Fabrizi, E., Ferrante, M. R., and Trivisano, C. (2016). Bayesian Beta Regression Models for the Estimation of Poverty and Inequality Parameters in Small Areas. In Pratesi, M., editor, Analysis of Poverty Data by Small Area Estimation, pages 299–314. John Wiley & Sons, Ltd.
- Fauzi, R. R. and Maesono, Y. (2023). Statistical Inference Based on Kernel Distribution Function Estimators.
 SpringerBriefs in Statistics. Springer Nature Singapore, Singapore.
- Felsenthal, D. S. (2012). Review of Paradoxes Afflicting Procedures for Electing a Single Candidate. In Felsenthal, D. S. and Machover, M., editors, Electoral Systems: Paradoxes, Assumptions, and Procedures, pages 19–91. Springer, Berlin, Heidelberg.

References VI

- Felsenthal, D. S. and Machover, M., editors (2012). Electoral Systems: Paradoxes, Assumptions, and Procedures. Studies in Choice and Welfare. Springer, Berlin, Heidelberg.
- González-Manteiga, W., Lombardía, M. J., Molina, I., Morales, D., and Santamaría, L. (2007). Estimation of the mean squared error of predictors of small area linear parameters under a logistic mixed model. Computational Statistics & Data Analysis, 51:2720–2733.
- González-Manteiga, W., Lombardía, M. J., Molina, I., Morales, D., and Santamaría, L. (2008). Bootstrap mean squared error of small-area eblup. Journal of Statistical Computation and Simulation, 78:443–462.
- Green-Armytage, J., Tideman, T. N., and Cosman, R. (2016). Statistical evaluation of voting rules. Social Choice and Welfare, 46(1):183–212.

References VII

- Greene, W. (2012). Econometric analysis. Pearson series in economics. Prentice Hall, Boston Munich, 7. ed edition.
- Gunawan, F. E., Budiman, A. S., Pardamean, B., Juana, E., Romeli, S., Cenggoro, T. W., Purwandari, K., Hidayat, A. A., Redi, A. A., and Asrol, M. (2023). Multivariate Time Series Deep Learning for Joint Prediction of Temperature and Relative Humidity in a Closed Space. Procedia Computer Science, 227:1046–1053.
- Hastie, T., Tibshirani, R., and Friedman, J. (2009). The Elements of Statistical Learning. Springer Series in Statistics. Springer, New York, NY.
- Henderson, C. R. (1950). Estimation of genetic parameters (Abstract). Annals of Mathematical Statistics, 21:309–310.
- Hobza, T. and Morales, D. (2016). Empirical Best Prediction Under Unit-Level Logit Mixed Models. Journal of Official Statistics, 32(3):661–692.

References VIII

- James, G., Witten, D., Hastie, T., and Tibshirani, R. (2013). An Introduction to Statistical Learning with Applications in R, volume 103 of Springer Texts in Statistics. Springer, New York, NY.
- Jiang, J. (2007). Linear and generalized linear mixed models and their applications. Springer series in statistics. Springer, New York.
- Kemm, F. (2023). Why Majority Judgement is not yet the solution for political elections, but can help finding it. arXiv:2302.10858.
- Levy, H. (1990). Stochastic Dominance. In Eatwell, J., Milgate, M., and Newman, P., editors, Utility and Probability, pages 251–254. Palgrave Macmillan UK, London.
- Matthews, S. and Hartman, B. (2022). Machine learning in ratemaking, an application in commercial auto insurance. Risks, 10(4):80.

- Molina, I. and Rao, J. N. K. (2010). Small area estimation of poverty indicators. Canadian Journal of Statistics, 38(3):369–385.
- Royall, R. M. (1976). The Linear Least-Squares Prediction Approach to Two-Stage Sampling. Journal of the American Statistical Association, 71(355):657–664.
- Thai, H.-T., Mentré, F., Holford, N. H., Veyrat-Follet, C., and Comets, E. (2013). A comparison of bootstrap approaches for estimating uncertainty of parameters in linear mixed effects models. Pharmaceutical Statistics, 12(3):129–140.
- Valliant, R., Dorfman, A. H., and Royall, R. M. (2000). Finite Population Sampling and Inference: A Prediction Approach. Wiley-Interscience, New York.

References X

- van Setten, M., Veenstra, M., Nijholt, A., and van Dijk, B. (2004). Case-Based Reasoning as a Prediction Strategy for Hybrid Recommender Systems. In Favela, J., Menasalvas, E., and Chávez, E., editors, Advances in Web Intelligence, pages 13–22, Berlin, Heidelberg. Springer.
- Vovk, V. (2008). Leading strategies in competitive on-line prediction. Theoretical Computer Science, 405(3):285–296.
- Wolny-Dominiak, A. and Żądło, T. (2022). On bootstrap estimators of some prediction accuracy measures of loss reserves in a non-life insurance company. Communications in Statistics - Simulation and Computation, 51(8):4225–4240.
- Żądło, T. (2013). On parametric bootstrap and alternatives of MSE. In Vojáčková, H., editor, Proceedings of 31st International Conference Mathematical Methods in Economics 2013, pages 1081–1086. The College of Polytechnics Jihlava, Jihlava.

 Żądło, T. (2020). On Accuracy Estimation Using Parametric Bootstrap in small Area Prediction Problems. Journal of Official Statistics, 36(2):435–458.



APPENDIX

æ

イロト イヨト イヨト イヨト

Accuracy measures matrix A- the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	30,409.52	92,010.24	30,525.97	67,948.94	75,471.81	91,967.10
$M_6, \theta_1, RMSE$	33,892.15	82,222.11	33,973.64	79,599.19	78,954.10	82,234.57
$M_1, \theta_2, RMSE$	916.26	548.11	916.13	413.71	613.53	508.82
$M_6, \theta_2, RMSE$	1,061.72	350.82	1,062.28	360.62	531.79	325.74
$M_1, \theta_1, QAPE_{0.5}$	20,337.75	86,634.24	20,583.34	60,212.39	62,486.63	87,039.66
$M_6, \theta_1, QAPE_{0.5}$	23,137.12	74,980.98	23,372.24	72,309.64	67,400.49	74,869.13
$M_1, \theta_2, QAPE_{0.5}$	829.49	388.74	828.17	280.48	415.84	351.43
$M_6, \theta_2, QAPE_{0.5}$	999.68	228.70	998.64	239.17	356.18	211.63
$M_1, \theta_1, QAPE_{0.95}$	60,198.47	135,643.60	60,587.21	112,127.20	132,336.46	133,635.47
$M_6, \theta_1, QAPE_{0.95}$	66,258.19	129,184.87	66,403.74	126,818.35	136,122.08	127,664.58
$M_1, \theta_2 QAPE_{0.95}$	1,481.50	1,051.47	1,479.56	808.35	1,201.03	984.06
$M_6, \theta_2, QAPE_{0.95}$	1,603.75	693.73	1,606.65	716.80	1,047.93	647.50

First-past-the-post voting matrix \mathbf{W}_1 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	1	0	0	0	0	0
$M_6, \theta_1, RMSE$	1	0	0	0	0	0
$M_1, \theta_2, RMSE$	0	0	0	1	0	0
$M_6, \theta_2, RMSE$	0	0	0	0	0	1
$M_1, \theta_1, QAPE_{0.5}$	1	0	0	0	0	0
$M_6, \theta_1, QAPE_{0.5}$	1	0	0	0	0	0
$M_1, \theta_2, QAPE_{0.5}$	0	0	0	1	0	0
$M_6, \theta_2, QAPE_{0.5}$	0	0	0	0	0	1
$M_1, \theta_1, QAPE_{0.95}$	1	0	0	0	0	0
$M_6, \theta_1, QAPE_{0.95}$	0	0	1	0	0	0
$M_1, \theta_2 QAPE_{0.95}$	1	0	0	0	0	0
$M_6, \theta_2, QAPE_{0.95}$	0	0	0	0	0	1
sum	14	5	7	3	1	6

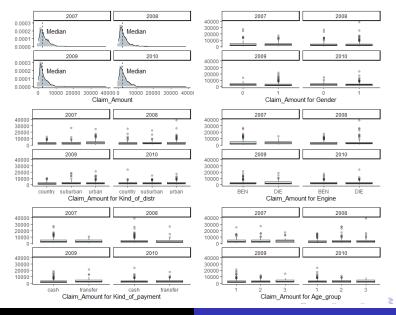
Positional voting matrix W_2 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	6	1	5	4	3	2
$M_6, \theta_1, RMSE$	6	2	5	3	4	1
$M_1, \theta_2, RMSE$	1	4	2	6	3	5
		•••				
$M_6, \theta_2, RMSE$	2	5	1	4	3	6
$M_1, \theta_1, QAPE_{0.5}$	6	2	5	4	3	1
$M_6, \theta_1, QAPE_{0.5}$	6	1	5	3	4	2
$M_1, \theta_2, QAPE_{0.5}$	1	4	2	6	3	5
				•••		
$M_6, \theta_2, QAPE_{0.5}$	1	5	2	4	3	6
$M_1, \theta_1, QAPE_{0.95}$	6	1	5	4	3	2
$M_6, \theta_1, QAPE_{0.95}$	6	2	5	4	1	3
$M_1, \theta_2 QAPE_{0.95}$	1	4	2	6	3	5
$M_6, \theta_2, QAPE_{0.95}$	2	5	1	4	3	6
median	5	4	4	3	3	3

Scaled voting matrix W_3 - the short form

voter	strat 1	strat 2	strat 3	strat 4	strat 5	strat 6
$M_1, \theta_1, RMSE$	1.000	0.000	0.998	0.391	0.268	0.001
$M_6, \theta_1, RMSE$	1.000	0.000	0.998	0.055	0.068	0.000
$M_1, \theta_2, RMSE$	0.000	0.733	0.000	1.000	0.602	0.811
$M_6, \theta_2, RMSE$	0.001	0.966	0.000	0.953	0.720	1.000
$M_1, \theta_1, QAPE_{0.5}$	1.000	0.006	0.996	0.402	0.368	0.000
$M_6, \theta_1, QAPE_{0.5}$	1.000	0.000	0.995	0.052	0.146	0.002
$M_1, \theta_2, QAPE_{0.5}$	0.000	0.803	0.002	1.000	0.753	0.871
$M_6, \theta_2, QAPE_{0.5}$	0.000	0.978	0.001	0.965	0.817	1.000
$M_1, \theta_1, QAPE_{0.95}$	1.000	0.000	0.995	0.312	0.044	0.027
$M_6, \theta_1, QAPE_{0.95}$	1.000	0.099	0.998	0.133	0.000	0.121
$M_1, \theta_2 QAPE_{0.95}$	0.000	0.639	0.003	1.000	0.417	0.739
$M_6, \theta_2, QAPE_{0.95}$	0.003	0.952	0.000	0.928	0.583	1.000
median	0.999	0.454	0.997	0.650	0.318	0.401

Automobile portfolio example



~ ~ ~ ~ ~